

## AIOF3\_BRUSHED Flight Control Board Built-in OSD Frsky Receiver

The AIOF3\_BRUSHED flight controller is a Highly integrated F3 flight controller both for Indoor FPV flight and outdoor FPV.

The flight controller integrate OSD and Receiver, run Betaflight firmware. It's amazing, you only just get ready your VTX and camera, it's simple to DIY a whole FPV racing Quadcopter with brushed motor .

### 1. Specification:

Brand Name: Eachine

Size: 38mm\*19mm

Weight: 3g

Processor: STM32 F303 MCU

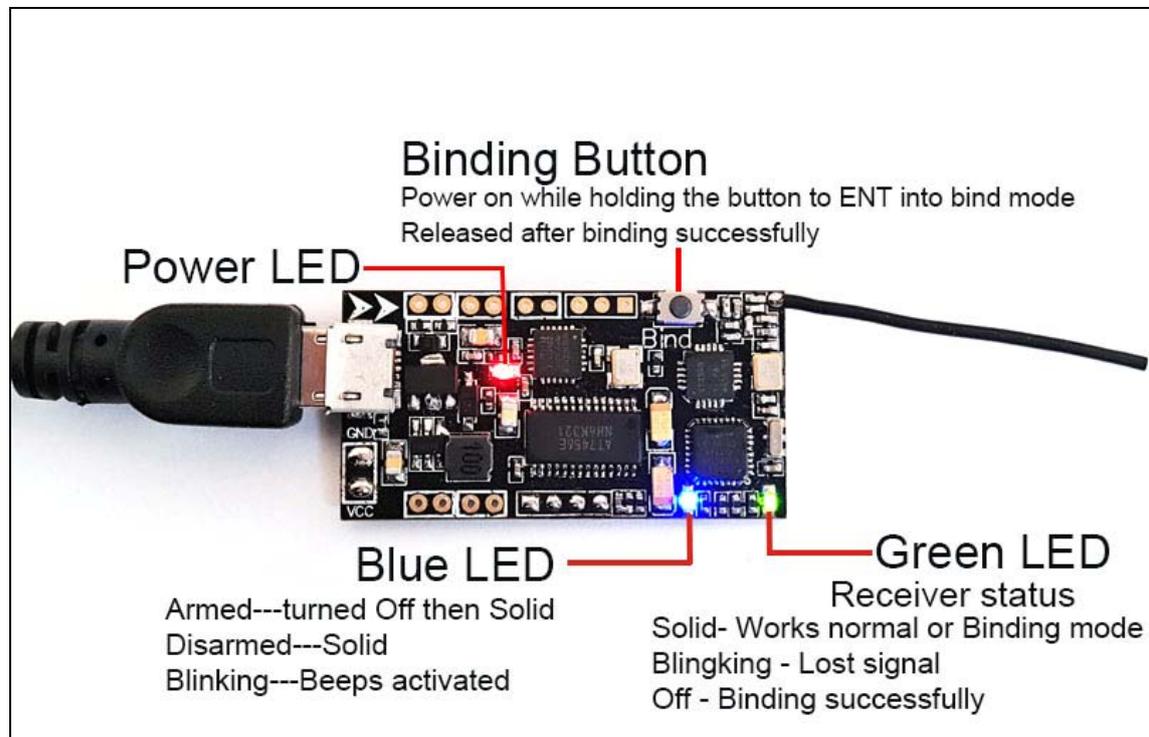
Sensor: SPI Sensor MPU6000

Target: Omnibus

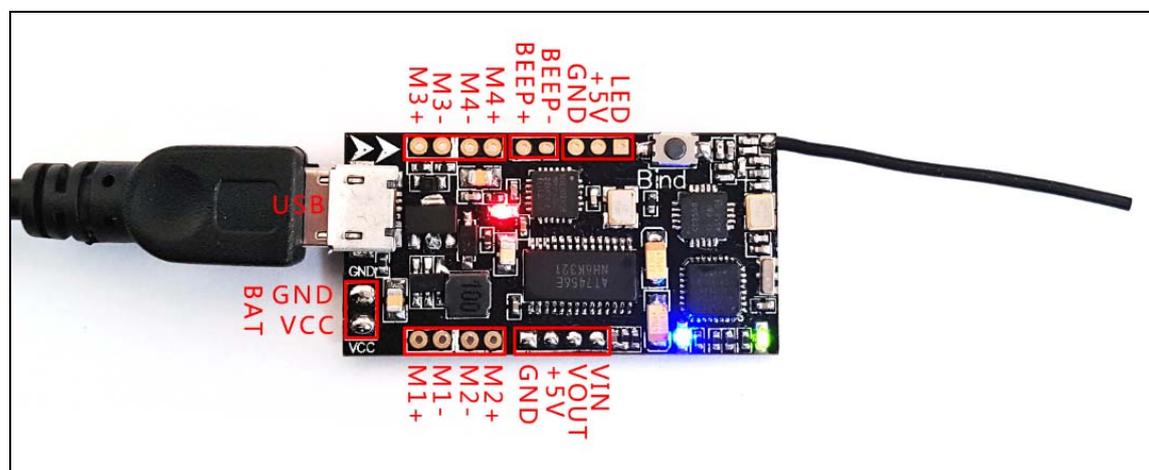
Firmware Version: Betaflight 3.0.1

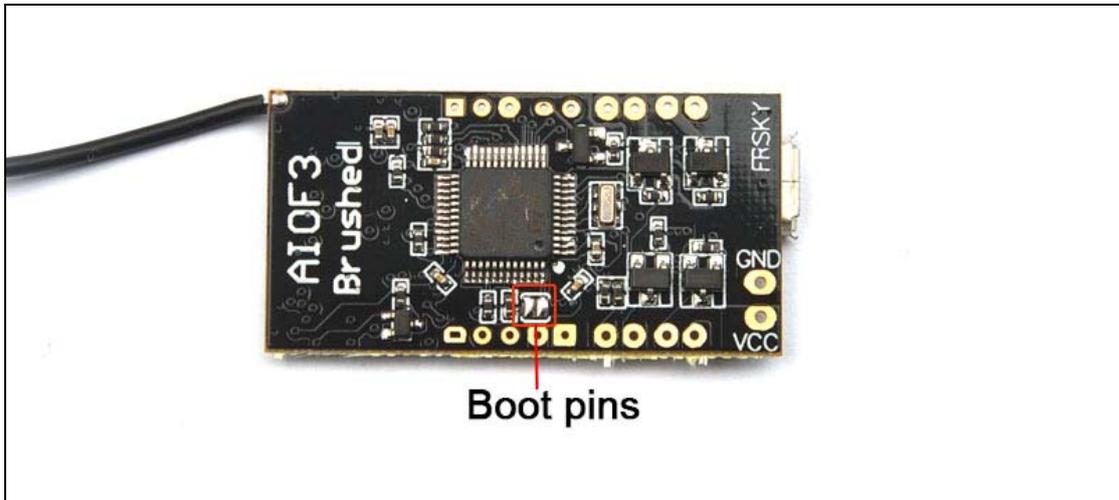
Receiver: Frsky D8 mode SBUS Output 8ch With RSSI output (OSD display Channle9 / X9D telemetry)

### 2. Connector and LED Definition:



### 3. Installation and Connection diagram:





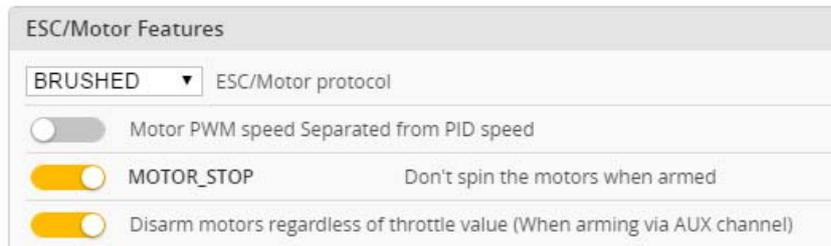
#### 4. Betaflight configuration:

All the configuration was set up before shipping, if you need to flash firmware and select "Full chip erase", you should reconfigure for the AIOF3 Flight controller board according to the bellowing diagram.

 After you flashed firmware and do the "Full chip erase" option, Please remove the propeller from the motor and plug your battery ,otherwise it maybe can't connected to the Betaflight configurator.

Reconfigure steps:

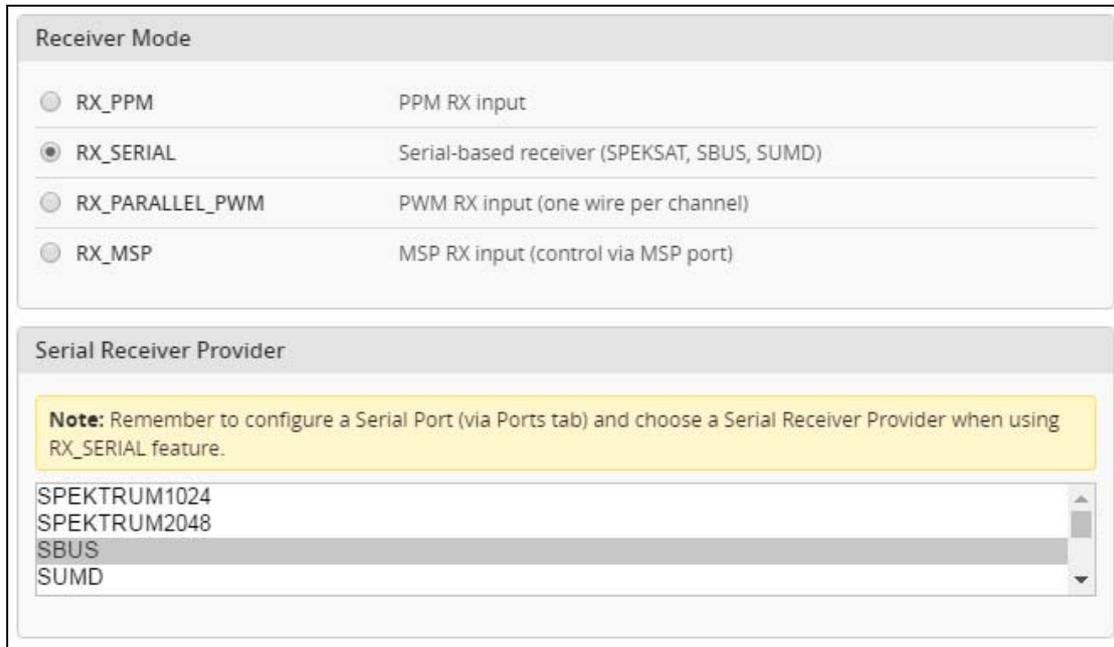
Go to Configure Tab and set ESC/Motor protocol to BRUSHED



\*This step is in order to avoid motor auto-spinning when connect the battery

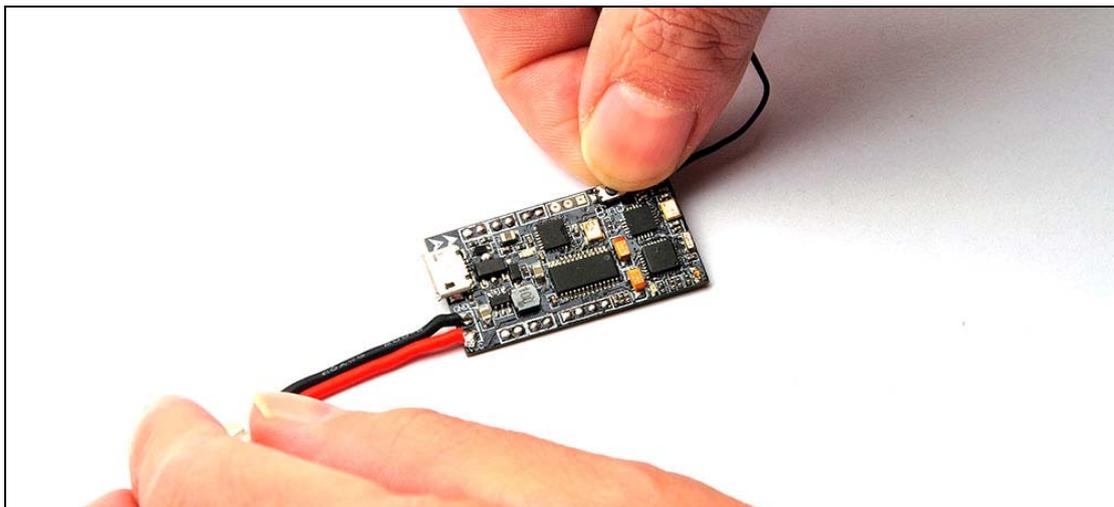
1. Ports and receiver mode sets like the bellowing diagram: First Enable Serial\_RX for uart3 and Set Receiver mode RX\_SERIAL , Select SBUS signal in Betaflight configurator.

Identifier	Data	Logging	Telemetry	RX	GPS
USB VCP	<input checked="" type="checkbox"/> MSP 115200 ▼	<input type="checkbox"/> Blackbox 115200 ▼	Disabled ▼ AUTO ▼	<input type="checkbox"/> Serial RX	<input type="checkbox"/> 57600 ▼
UART1	<input type="checkbox"/> MSP 115200 ▼	<input type="checkbox"/> Blackbox 115200 ▼	Disabled ▼ AUTO ▼	<input type="checkbox"/> Serial RX	<input type="checkbox"/> 57600 ▼
UART2	<input type="checkbox"/> MSP 115200 ▼	<input type="checkbox"/> Blackbox 115200 ▼	Disabled ▼ AUTO ▼	<input type="checkbox"/> Serial RX	<input type="checkbox"/> 57600 ▼
UART3	<input type="checkbox"/> MSP 115200 ▼	<input type="checkbox"/> Blackbox 115200 ▼	Disabled ▼ AUTO ▼	<input checked="" type="checkbox"/> Serial RX	<input type="checkbox"/> 57600 ▼



2. Binding Procedure:

a) Power for the AIOF3\_Brushed board while holding the Bind button, the Green LED will get to be solid, this means the AIOF3\_Brushed is in binding mode, then release the button.



b) Turn on your Radio and select D8 mode for the Receiver. Then Go to the Receiver [Bind] option, and ENT to Binding with the AIOF3\_Brushed. The Green LED will turn off, this indicates binding successfully. Reconnect the battery to the AIOF3\_Brushed board after Binding successfully.



3. The default receiver channel map is TAER1234, please ensure your transmitter is matched with it, otherwise it can't be armed.

<b>Channel Map</b>	<b>RSSI Channel</b>
TAER1234	Disabled

- The Default Arm/Disarm switch is AUX1(Channel 5),and you can also customize it with Betaflight Configurator.

Modes WIKI

Use ranges to define the switches on your transmitter and corresponding mode assignments. A receiver channel that gives a reading between a range min/max will activate the mode. Remember to save your settings using the Save button.

<b>ARM</b>	AUX 1	
<b>AIR MODE</b>	AUX 2	
<b>ANGLE</b>	AUX 2	

- Set Arm/Disarm switch for your TARANIS X9D: Move to the MIXER interface, Set “SA” or “SB” switch etc. for Ch5 to ARM/DISARM the motor.



- Toggle the AUX1 Switch and the blue LED on the board will first turning off and get be solid soon, this indicate the motor was armed. Be careful and enjoy your flight now!

### 5. OSD configuration:

Connect the AIOF3 board to the computer , open Betaflight Configurator , move to the OSD option

OSD WIKI

<b>Elements</b>	<b>Preview (drag to change position)</b>	<b>Video Format</b>
<input checked="" type="checkbox"/> Rssi Value <input checked="" type="checkbox"/> Main Batt Voltage <input checked="" type="checkbox"/> Crosshairs <input checked="" type="checkbox"/> Artificial Horizon <input checked="" type="checkbox"/> Horizon Sidebars <input checked="" type="checkbox"/> Overtime <input checked="" type="checkbox"/> Flytime <input checked="" type="checkbox"/> Flymode <input checked="" type="checkbox"/> Craft Name <input type="checkbox"/> Throttle Position		<input checked="" type="radio"/> AUTO <input type="radio"/> PAL <input type="radio"/> NTSC <input checked="" type="radio"/> IMPERIAL <input type="radio"/> METRIC <b>Alarms</b> 20 Rssi 2200 Capacity 10 Minutes 100 Altitude
		<input type="button" value="Font Manager"/> <input type="button" value="Save"/>

RSSI output use Channel 9 , configure in Betaflight receiver option

Channel Map		RSSI Channel
TAER1234		9
RC Deadband	Yaw Deadband	
0	0	
RC Interpolation		
Auto		RC Interpolation ?

Craft Name set in configuration option

1460	3D Neutral
0	3D Deadband Throttle
Misc	
Eachine AIOF3	Craft name