

Notes

1. The receiver signal will be unstable while the MSP (Connect to Betaflight) Connection established 2. The PID loop frequency must be 2kHZ at this firmware version, will update soon.



Specifications	
Brand Name: Happymodel	
Mode Name: Snapper7	
Item Name: 1S Brushless Whoop racer drone BNF	
Wheelbase: 75mm	
Size: 98.5mm*98.5mm*36mm	
Weight: 28g(without battery)	

Features	
Betaflight support , multi flight mode: ACRO/AIR/ANGLE	
Powerful Brushless motor and Smooth ESC	
CNC aluminum alloy propeller guard	
Betaflight OSD support ,easy to get Voltage and other info from your goggles	
Built-in DSMX/DSM2 Compatible satellite receiver	
Head lights ready	
Camera angle adjustable	
3	

Components	Quantity	Part. NO.
Snapper7 Frame	1	SP701
Snapper7 Canopy	1	SP702
0703 KV19000 motor	4	SP703
4 x 40mm Propeller	2	SP704
Crazybee F3 Flight controllr	1	SP705DX
3-IN-1 AIO vtx&camera	1	SP706
3.8v HV Lipo Battery	0	SP707
1S HV USB Charger	1	SP708
6-IN-1 Charger	0	SP708
Propeller tools	1	SP709

VTX Bands and Channels setup

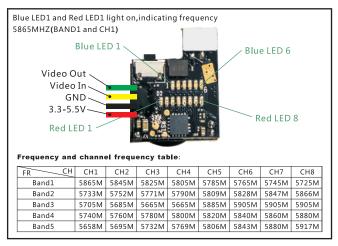
Frequency switching:

By one button, Short press the button to change channel, 1-8 adjustable. Press and hold the button for 2s to change bands, 1-6 adjustable.

Two groups of LEDs:

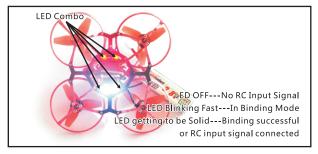
Group 1:6 BLUE LED stand for bands

Group 2:8 RED LED stand for channels



Binding procedure

- (1)Connect Crazybee F3 DSM2/DSMX Version to computer and open Betaflight configurator, From CLI tab type: "set spektrum_sat_bind = 9" for DSMX radio or "set spektrum_sat_bind = 5" for DSM2 radio
- (2)Type "save" and after Flight controller reboot remove USB cable (=Power off the board) (3)Wait a second and reconnect the USB cable. After cold start satellite led combo on the backside of the board (2 red led+2 white led) should start blinking and transmitter should be turned on while pressing the bind button
- (4)After binding satellite LED combo should be solid. Connect Betaflight and use receiver tab to test that satellite is working correctly.
- (5)Final step is to go to CLI tab and type "set spektrum_sat_bind = 0" and then type "save". This must be done so that satellite doesn't go back to binding mode when the flight controller is repowered again.



Entering CLI Mode, type 'exit' to return, or 'help' # Set spektrum_sat_bind=9 spektrum_sat_bind set to 9 # save Entering CLI Mode, type 'exit' to return, or 'help' # Set spektrum_sat_bind=5 spektrum_sat_bind set to 5 # save Entering CLI Mode, type 'exit' to return, or 'help' # Set spektrum_sat_bind=0 spektrum_sat_bind=0 spektrum_sat_bind=0 # set spektrum_sat_bind set to 0 # save

Receiver configuration

We have configured the DSM2/DSMX receiver for the Snapper 7 before shipping. If you flashed the firmware, Please setup as the following steps: Enable Serial, RX for UART3, then select RX_SERIAL from the RECEIVER Mode and set the Serial Receiver Provider to be Spektrum1024 for DSMX radio and Spektrum2048 for DSMX Radio in Betaflight Configurator.



Arm/Disarm the Motor

1. The Default Arm/Disarm switch for Snapper 7 is AUX1 (Channel 5), and you can also customize it with Betaflight Configurator.



2.For most of Spektrum radio the default channel 5 is Gear switch and you can also customize it. Use DX9 for example, Go to menu and select System setup , then choose Channel ssign.

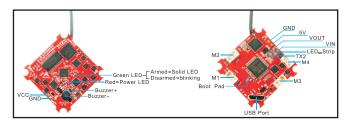


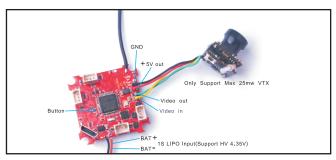
3.The default channel map for Snapper 7 DSM2/X version is TAER1234, please make sure your transmitter is matched, otherwise it will can't be armed. Toggle the AUX1 Switch ,the Green LED on the flight controller will getting to be solid, this indicates the motor was armed . And also you can found "Armed" displayed on your FPV Goggles or the FPV Monitor. Please make sure keep the Snapper 7 level before arming .Be careful and enjoy your flight now!



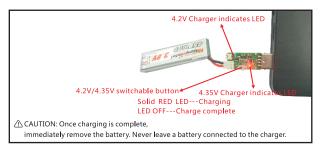


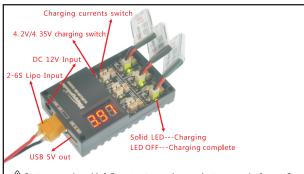
Flight controller connection diagram





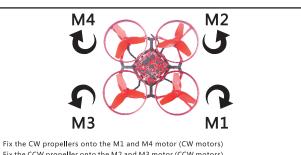
Charger the Lipo Battery





Ports are numbered 1-6. Do not put more than one battery on a single port. For example: do not insert one battery on the Picoblade 1.25 plug and another on the same port with the PH 2.0 plug.

Mixer type and ESC/motor protocol



Fix the CCW propeller onto the M2 and M3 motor (CCW motors)



ESC Check and Flash firmware

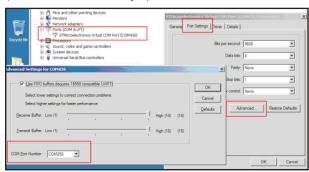
1.Download New release Blhelisuite from:

https://www.mediafire.com/folder/dx6kfaasyo24l/BLHeliSuite

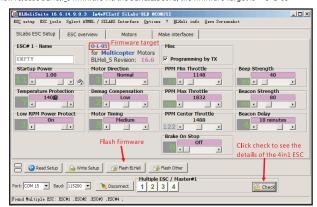
 $2. Connect the \, \mathsf{CRAZYBEE} \, flight \, controller \, to \, computer \, and \, power \, for \, it \, with \, \mathsf{1S} \, \mathsf{Lipo} \, \mathsf{battery}$



3. Open the Device Manager of your computer, find the Ports, please make sure the Comport Serial Number is under 255, otherwise it will can't connect to the BLHELISUITE. You can change the port serial number like the bellowing step :



4.Open the BLHELISUITE, Select SILABS BLHeli Bootloader (Cleanflight) from the third tab on the top side. Then Select the right Serial com port and Click connect. You can also Flash the new release BLHeli_s firmware via the BLHEILISUITE, the firmware Target is "O-L-05"



Flight controller firmware update

1.Install latest STM32 Virtual COM Port Driver

http://www.st.com/web/en/catalog/tools/PF257938

2.Install STM BOOTLOAD Driver (STM Device in DFU MODE) 3.Open Betaflight configurator and choose firmware target "Crazybeef3DX", then select the

 $4. There \ are \ 2 \ ways \ to \ get \ in \ DFU \ Mode: 1). \ solder \ the \ boot \ pad \ and \ then \ plug \ USB \ to \ computer \ 2).$

loading betaflight firmware and hit "flash", then it will getting into DFU Mode automatically. 5.Open Zadig tools to replace the drivers from STM32 Bootloader to WINUSB Driver.

 $6. Reconnect the flight controller to the computer after replace driver done\,, and open\,$

Betaflight Configurator, loading firmware and flash.



*We will update the firmware for Crazybee F3 and release to our website in time.

Betaflight OSD Configurations

 $Connect the \ flight \ controller \ to \ the \ computer \ , \ open \ Betaflight \ Configurator \ , \ move \ to \ the \ OSD$ option, then you can configure the layout of the OSD.

