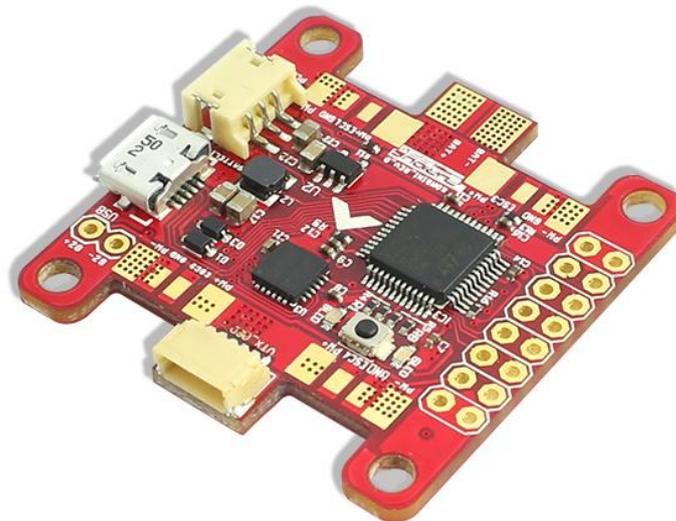




KOMBINI DSHOT VERSION

Flight controller

USER MANUAL



Please contact us if you need further assistance:

Tech support: tech@furiousfpv.com

Sales support: sales@furiousfpv.com

Website: <http://furiousfpv.com/>



Introduction

Designed nothing short of revolutionary, the Furious KOMBINI Flight Controller steps up the competition with feature packed insanity that is ready to alter your FPV world.

Unlike any other system available today, the Furious KOMBINI provides an all in one solution that brings forth the ultimate in simplified sophistication. This all encompassing FC solution utilizes industry leading technology that has never been seen in a system this compact and powerful - the ultimate end game for high powered FPV flight.

Cluttered & complex wiring? Never again. With an industry 1st gold plated PDB that is integrated within, the KOMBINI FC provides the ultimate in soldering ease with the highest grade of connectivity, allowing direct soldering points for motors, VTx, Receiver and FPV Camera. Rated with 150A of current protection @ 5S 18.5V input power, the KOMBINI is ready to push the boundaries of aggressive FPV flight.

Utilizing the very latest F3 chip processor with built in BetaFlight firmware, the Furious KOMBINI utilizes industry leading components with an included LC filter for the very best in signal reception. Add the 1A 5V BEC with a built in Sbus inverter & Spektrum satellite port, and the KOMBINI FC stand alone amongst all the rest with a potent blend of race ready madness.

Sized at 36mm x 36mm, the compact footprint of the KOMBINI FC is the perfect application of race ready aggression, providing a flight controller experience second to none. This adhesion of performance, capability & simplicity is the apex of FPV flight, providing the end user with a flight experience that brings everything to the table in a zero compromise design.

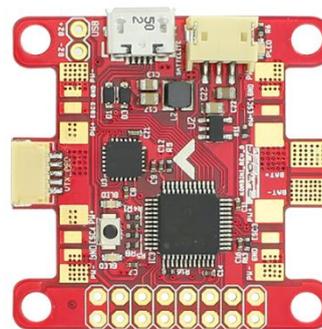
For the pinnacle in simplicity, performance and cutting edge capability, the Furious KOMBINI is the feature packed FC system that is ready and waiting to dominate. Get yours today, and change the way you FPV.

WHAT'S NEW KOMBINI DSHOT VERSION?

- Remove PPM pin and add TX3 pin For the pinnacle in simplicity, performance
- Ready support Dshot protocol
- New component for BEC better
- New red color for PCB

Feature

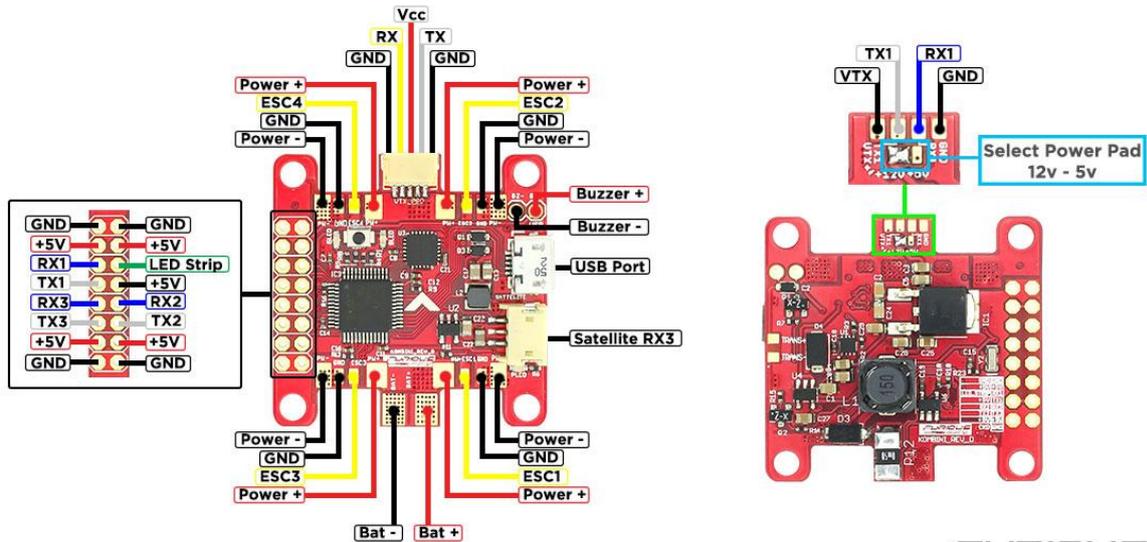
- Latest Generation F3 Processor Chip
- Simplicity Defined with Built In PDB
- Massive 150A PDB Current Protection
- LC Filter & 12v
- 800mA BEC for VTX



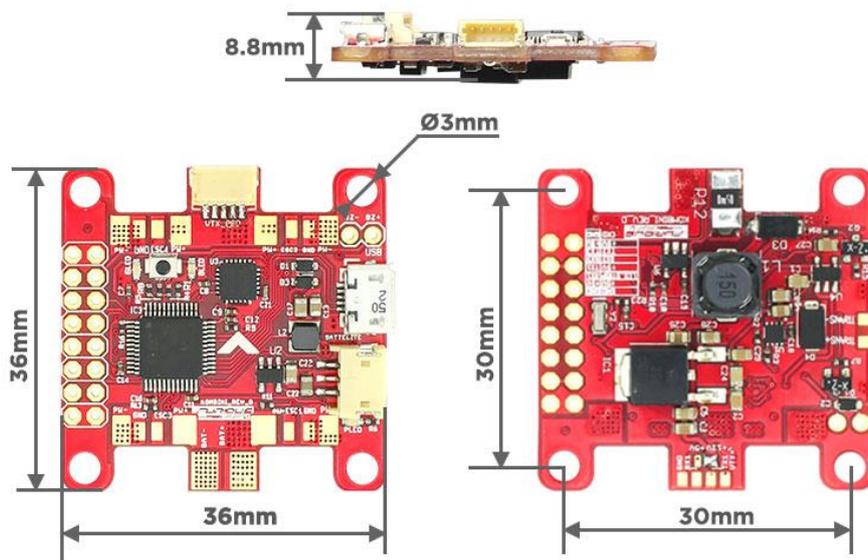
- 5S 18.5V Ready
- Heavy Duty 2A BEC @ 5V and 0.8A BEC @12V Output
- Ultra Compact Design for Ease of Installation
- Gold Plated Pads for the Very Best Connectivity
- Firmware Perfection via BetaFlight
- BLHeli Pass Through Setup
- Compact Sizing w/ 30.5mm x 30.5mm Mounting Holes
- Included Spektrum Satellite Port
- FrSky Telemetry, Ready & Waiting
- Full USB Support
- MPU6000 SP1 Chip
- Weight: 7gr



Board Layout



Dimensions



Connections

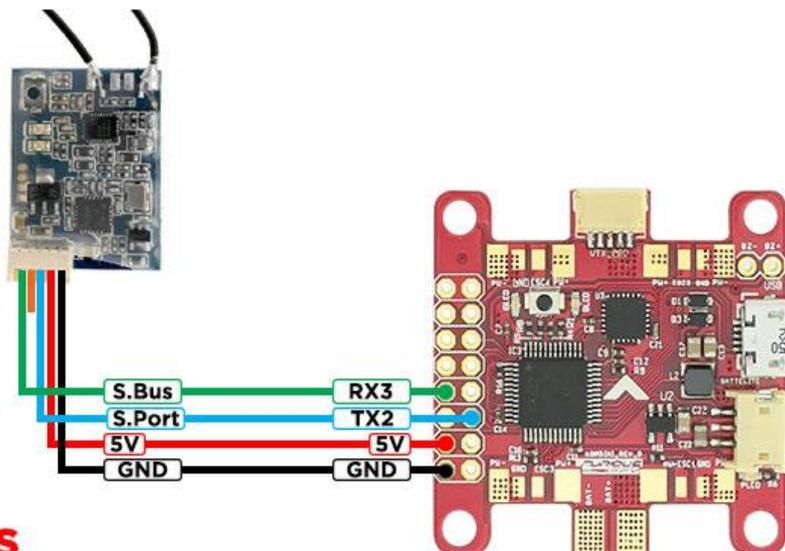
*** Warning:** Kombini DShot Version can support up to 5s Lipo battery but make sure other devices also support it.

Connect with Receiver:

- Using XSR FrSky Receiver

Port Identifier	Configuration	Serial Rx	Telemetry Output	Sensor Input
USB VCP	<input checked="" type="checkbox"/> MSP 115200 ▾	<input type="checkbox"/> Serial RX	Disabled ▾ AUTO ▾	Disabled ▾ AUTO ▾
UART1	<input type="checkbox"/> MSP 115200 ▾	<input type="checkbox"/> Serial RX	Disabled ▾ AUTO ▾	Disabled ▾ AUTO ▾
UART2	<input type="checkbox"/> MSP 115200 ▾	<input type="checkbox"/> Serial RX	SmartPort ▾ AUTO ▾	Disabled ▾ AUTO ▾
UART3	<input type="checkbox"/> MSP 115200 ▾	<input checked="" type="checkbox"/> Serial RX	Disabled ▾ AUTO ▾	Disabled ▾ AUTO ▾

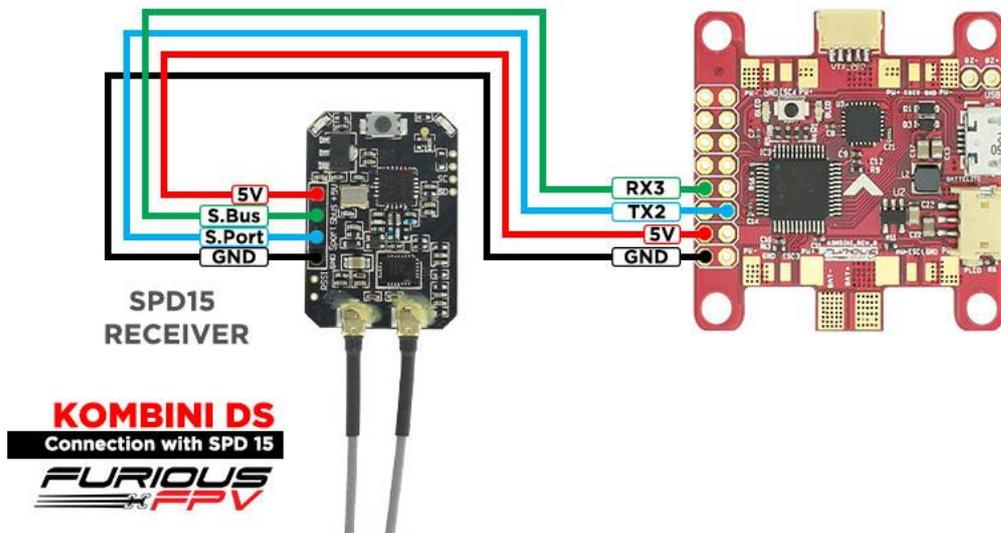
XSR RECEIVER



KOMBINI DS
 Connection with XSR FrSky

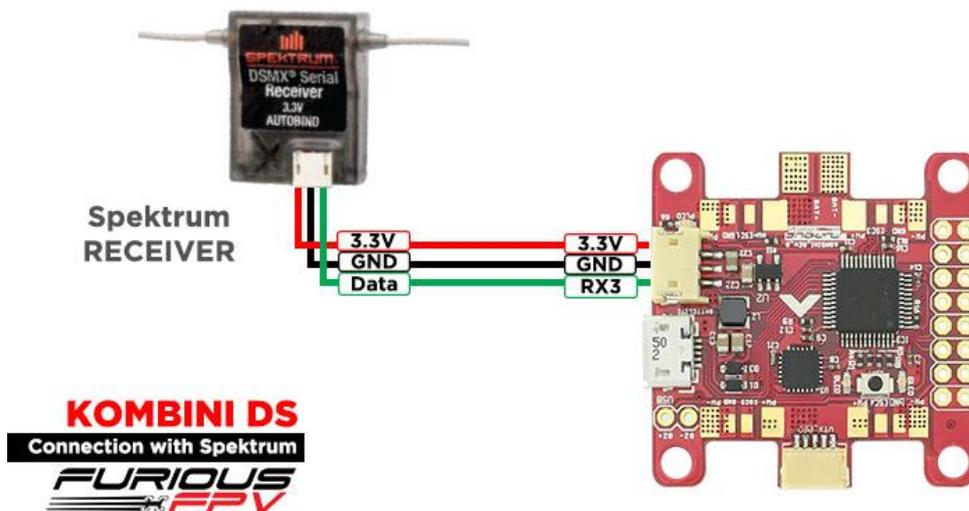
- Using SPD15 Receiver

Port Identifier	Configuration	Serial Rx	Telemetry Output	Sensor Input
USB VCP	<input checked="" type="checkbox"/> MSP 115200 ▾	<input type="checkbox"/> Serial RX	Disabled ▾ AUTO ▾	Disabled ▾ AUTO ▾
UART1	<input type="checkbox"/> MSP 115200 ▾	<input type="checkbox"/> Serial RX	Disabled ▾ AUTO ▾	Disabled ▾ AUTO ▾
UART2	<input type="checkbox"/> MSP 115200 ▾	<input type="checkbox"/> Serial RX	SmartPort ▾ AUTO ▾	Disabled ▾ AUTO ▾
UART3	<input type="checkbox"/> MSP 115200 ▾	<input checked="" type="checkbox"/> Serial RX	Disabled ▾ AUTO ▾	Disabled ▾ AUTO ▾



- Using Spektrum Satellite Receiver

Port Identifier	Configuration	Serial Rx	Telemetry Output	Sensor Input
USB VCP	<input checked="" type="checkbox"/> MSP 115200 ▾	<input type="checkbox"/> Serial RX	Disabled ▾ AUTO ▾	Disabled ▾ AUTO ▾
UART1	<input type="checkbox"/> MSP 115200 ▾	<input type="checkbox"/> Serial RX	Disabled ▾ AUTO ▾	Disabled ▾ AUTO ▾
UART2	<input type="checkbox"/> MSP 115200 ▾	<input type="checkbox"/> Serial RX	Disabled ▾ AUTO ▾	Disabled ▾ AUTO ▾
UART3	<input type="checkbox"/> MSP 115200 ▾	<input checked="" type="checkbox"/> Serial RX	Disabled ▾ AUTO ▾	Disabled ▾ AUTO ▾



Connect with Video Transmitter:

* **Warning:** Kombini DShot Version can support up to 5s Lipo battery but make sure other devices also support it.

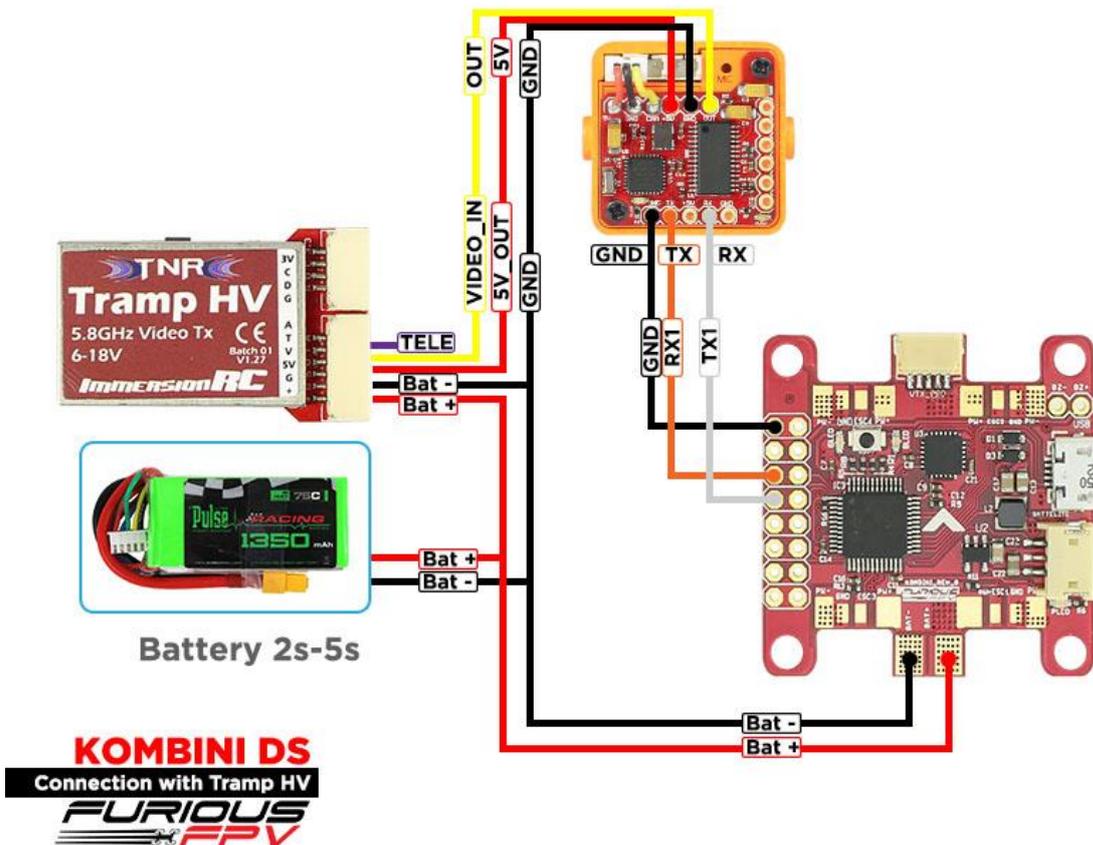
- Using Tramp HV

With Piggy V2 OSD

Ports

Note: not all combinations are valid. When the flight controller firmware detects this the serial port configuration will be reset.
 Note: Do NOT disable MSP on the first serial port unless you know what you are doing. You may have to reflash and erase your configuration if you do.

Port Identifier	Configuration	Serial Rx	Telemetry Output	Sensor Input	Peripherals
USB VCP	<input checked="" type="checkbox"/> MSP 115200	<input type="checkbox"/> Serial RX	Disabled AUTO	Disabled AUTO	Disabled AUTO
UART1	<input checked="" type="checkbox"/> MSP 115200	<input type="checkbox"/> Serial RX	Disabled AUTO	Disabled AUTO	Disabled AUTO
UART2	<input type="checkbox"/> MSP 115200	<input type="checkbox"/> Serial RX	Disabled AUTO	Disabled AUTO	Disabled AUTO
UART3	<input type="checkbox"/> MSP 115200	<input type="checkbox"/> Serial RX	Disabled AUTO	Disabled AUTO	Disabled AUTO

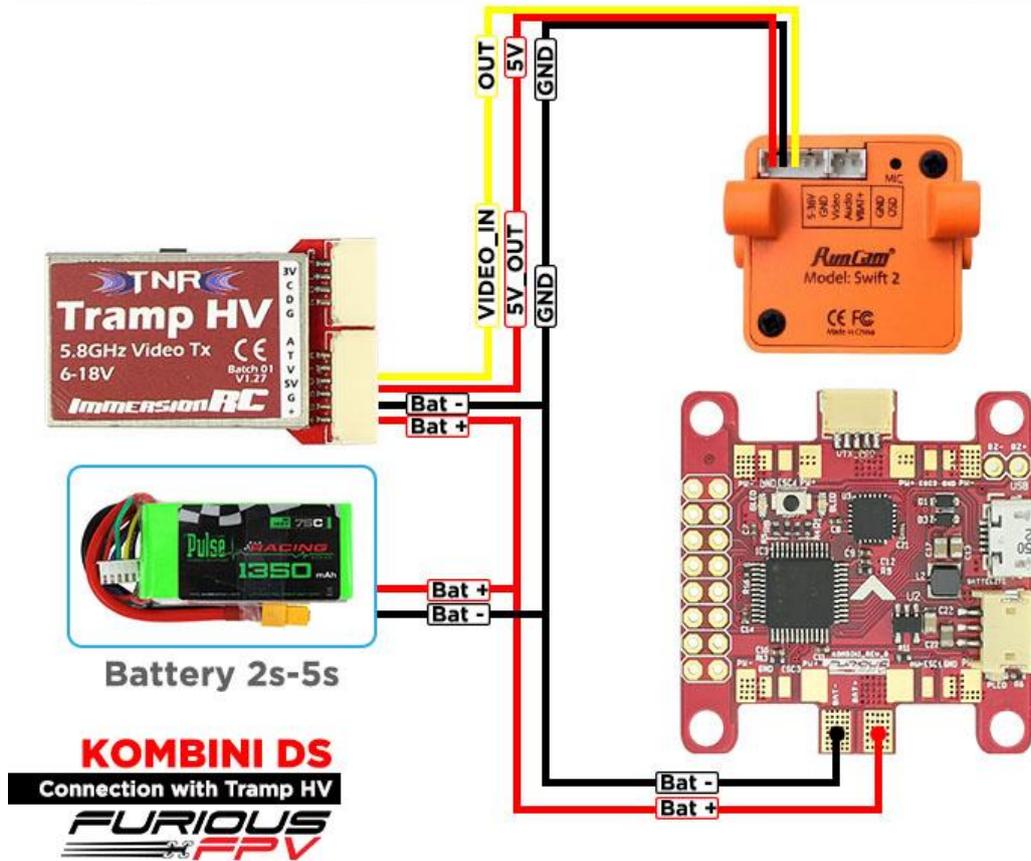


With Only Camera

Ports

Note: not all combinations are valid. When the flight controller firmware detects this the serial port configuration will be reset.
Note: Do **NOT** disable MSP on the first serial port unless you know what you are doing. You may have to reflash and erase your configuration if you do.

Port Identifier	Configuration	Serial Rx	Telemetry Output	Sensor Input	Peripherals
USB VCP	<input checked="" type="checkbox"/> MSP 115200 ▾	<input type="checkbox"/> Serial Rx	Disabled ▾ AUTO ▾	Disabled ▾ AUTO ▾	Disabled ▾ AUTO ▾
UART1	<input type="checkbox"/> MSP 115200 ▾	<input type="checkbox"/> Serial Rx	Disabled ▾ AUTO ▾	Disabled ▾ AUTO ▾	Disabled ▾ AUTO ▾
UART2	<input type="checkbox"/> MSP 115200 ▾	<input type="checkbox"/> Serial Rx	Disabled ▾ AUTO ▾	Disabled ▾ AUTO ▾	Disabled ▾ AUTO ▾
UART3	<input type="checkbox"/> MSP 115200 ▾	<input type="checkbox"/> Serial Rx	Disabled ▾ AUTO ▾	Disabled ▾ AUTO ▾	Disabled ▾ AUTO ▾



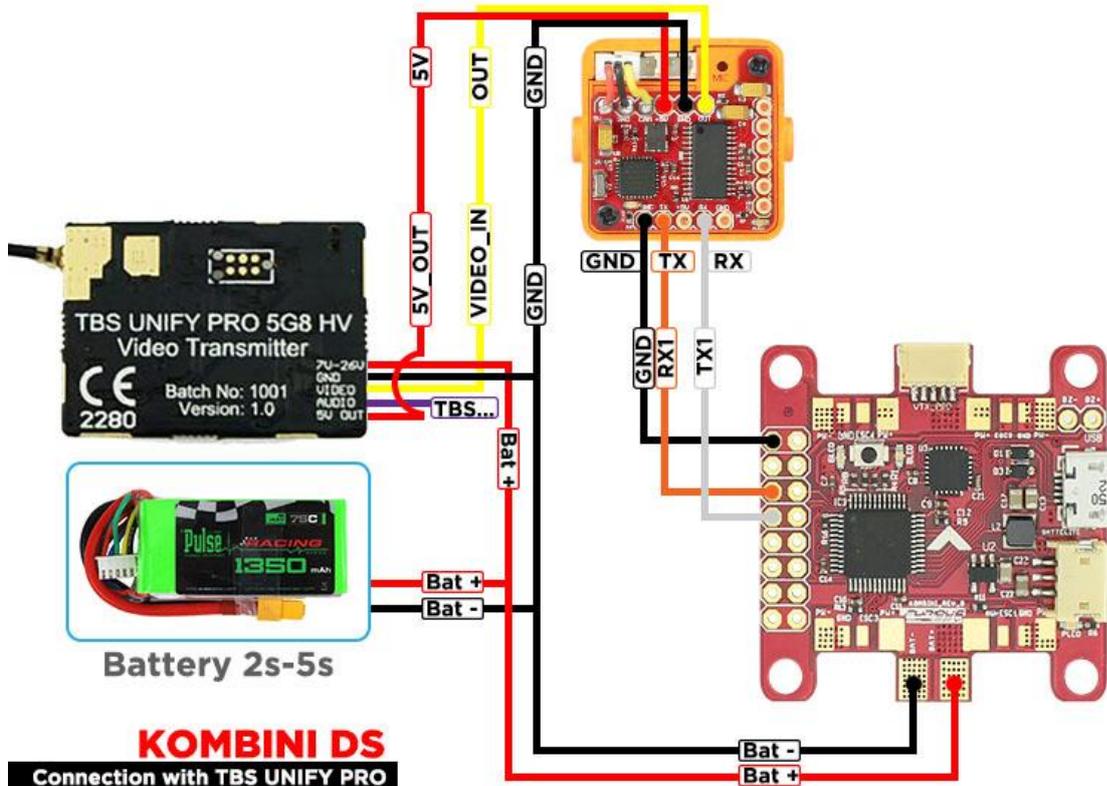
- Using TBS Unify Pro

With Piggy V2 OSD

Ports

Note: not all combinations are valid. When the flight controller firmware detects this the serial port configuration will be reset.
 Note: Do NOT disable MSP on the first serial port unless you know what you are doing. You may have to reflash and erase your configuration if you do.

Port Identifier	Configuration	Serial Rx	Telemetry Output	Sensor Input	Peripherals
USB VCP	<input checked="" type="checkbox"/> MSP 115200	<input type="checkbox"/> Serial Rx	Disabled AUTO	Disabled AUTO	Disabled AUTO
UART1	<input checked="" type="checkbox"/> MSP 115200	<input type="checkbox"/> Serial Rx	Disabled AUTO	Disabled AUTO	Disabled AUTO
UART2	<input type="checkbox"/> MSP 115200	<input type="checkbox"/> Serial Rx	Disabled AUTO	Disabled AUTO	Disabled AUTO
UART3	<input type="checkbox"/> MSP 115200	<input type="checkbox"/> Serial Rx	Disabled AUTO	Disabled AUTO	Disabled AUTO



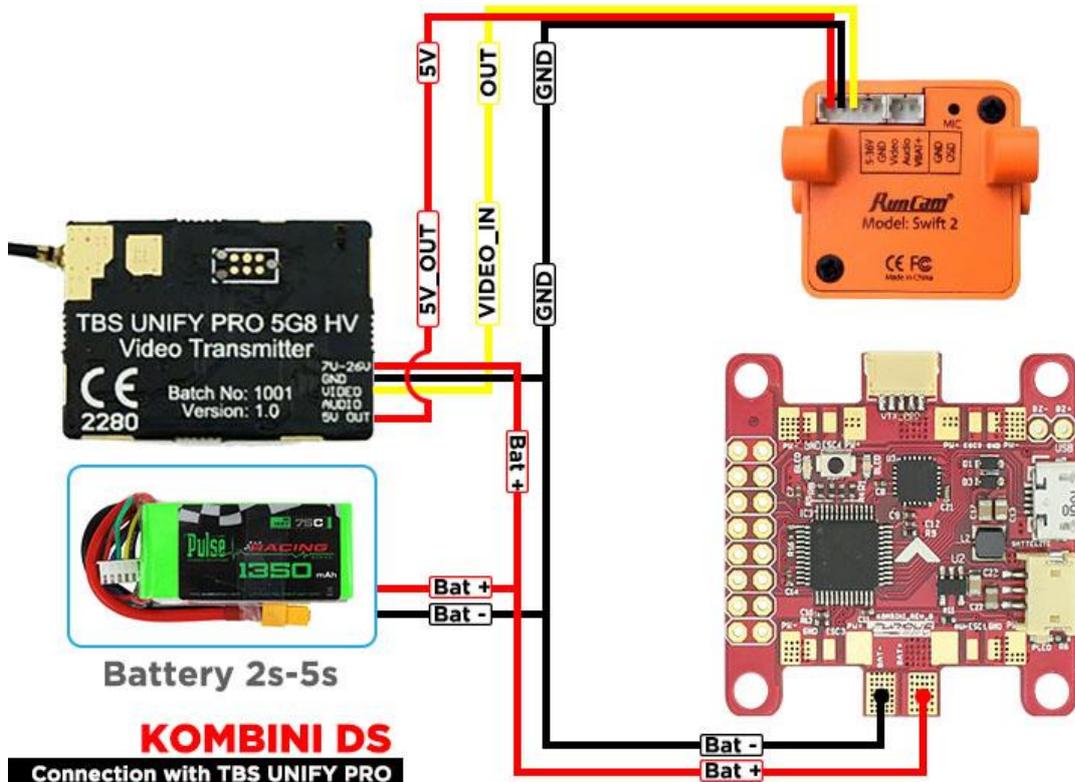
KOMBINI DS
 Connection with TBS UNIFY PRO

With Only Camera

Ports

Note: not all combinations are valid. When the flight controller firmware detects this the serial port configuration will be reset.
 Note: Do NOT disable MSP on the first serial port unless you know what you are doing. You may have to reflash and erase your configuration if you do.

Port Identifier	Configuration	Serial Rx	Telemetry Output	Sensor Input	Peripherals
USB VCP	<input checked="" type="checkbox"/> MSP 115200	<input type="checkbox"/> Serial Rx	Disabled AUTO	Disabled AUTO	Disabled AUTO
UART1	<input type="checkbox"/> MSP 115200	<input type="checkbox"/> Serial Rx	Disabled AUTO	Disabled AUTO	Disabled AUTO
UART2	<input type="checkbox"/> MSP 115200	<input type="checkbox"/> Serial Rx	Disabled AUTO	Disabled AUTO	Disabled AUTO
UART3	<input type="checkbox"/> MSP 115200	<input type="checkbox"/> Serial Rx	Disabled AUTO	Disabled AUTO	Disabled AUTO



Battery 2s-5s

KOMBINI DS
 Connection with TBS UNIFY PRO
FURIOUS
 FPV

- Using FX FX799T

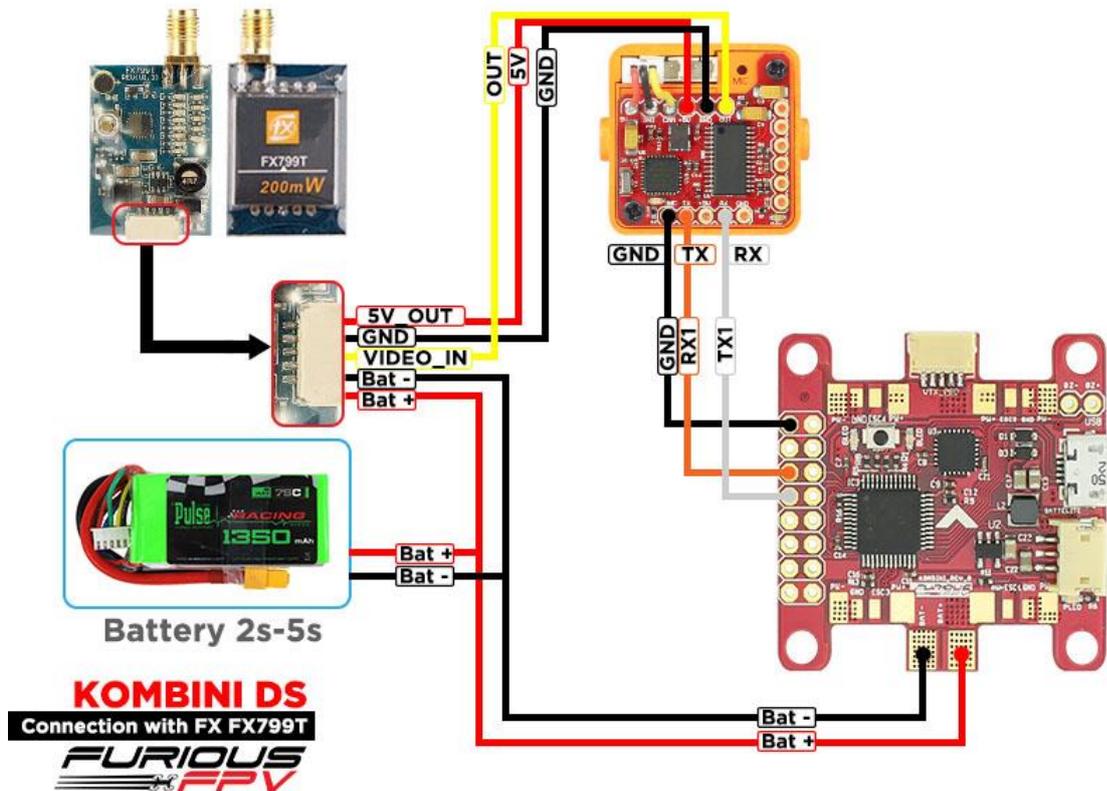
With Piggy V2 OSD

Ports

2003

Note: not all combinations are valid. When the flight controller firmware detects this the serial port configuration will be reset.
 Note: Do NOT disable MSP on the first serial port unless you know what you are doing. You may have to reflash and erase your configuration if you do.

Port Identifier	Configuration	Serial Rx	Telemetry Output	Sensor Input	Peripherals
USB VCP	<input checked="" type="checkbox"/> MSP 115200	<input type="checkbox"/> Serial RX	Disabled AUTO	Disabled AUTO	Disabled AUTO
UART1	<input checked="" type="checkbox"/> MSP 115200	<input type="checkbox"/> Serial RX	Disabled AUTO	Disabled AUTO	Disabled AUTO
UART2	<input type="checkbox"/> MSP 115200	<input type="checkbox"/> Serial RX	Disabled AUTO	Disabled AUTO	Disabled AUTO
UART3	<input type="checkbox"/> MSP 115200	<input type="checkbox"/> Serial RX	Disabled AUTO	Disabled AUTO	Disabled AUTO

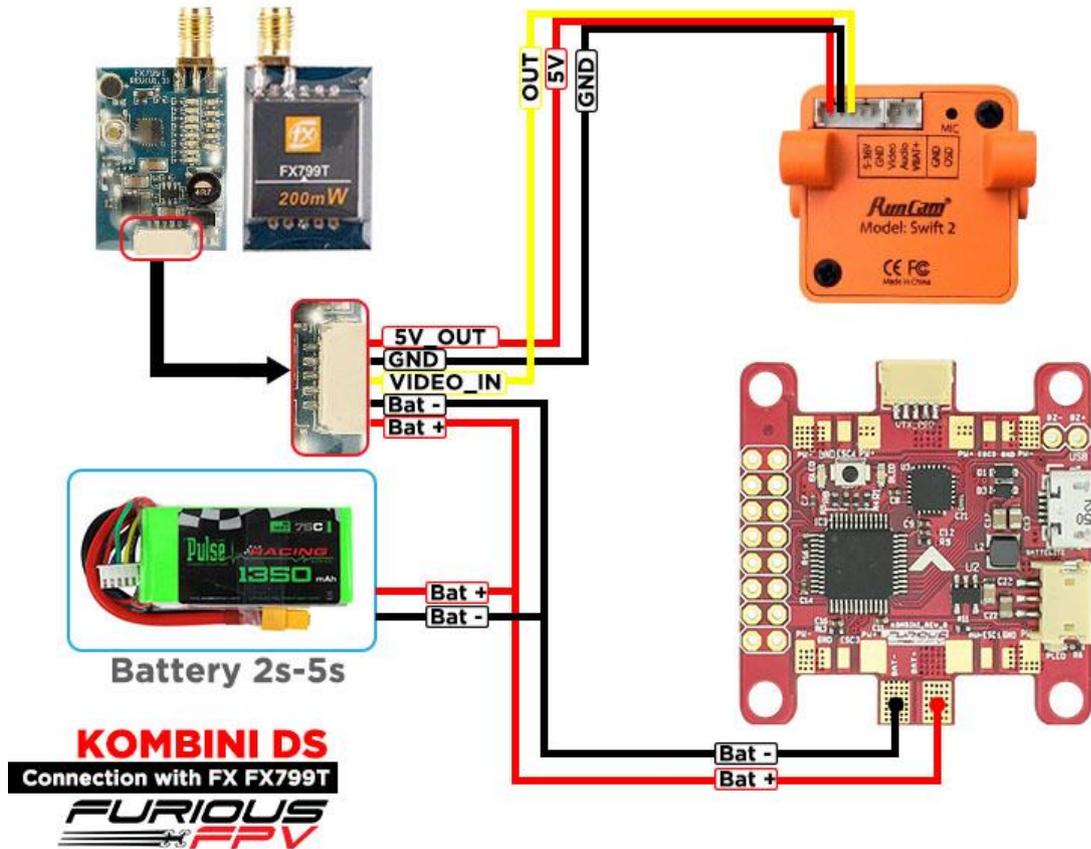


With Only Camera

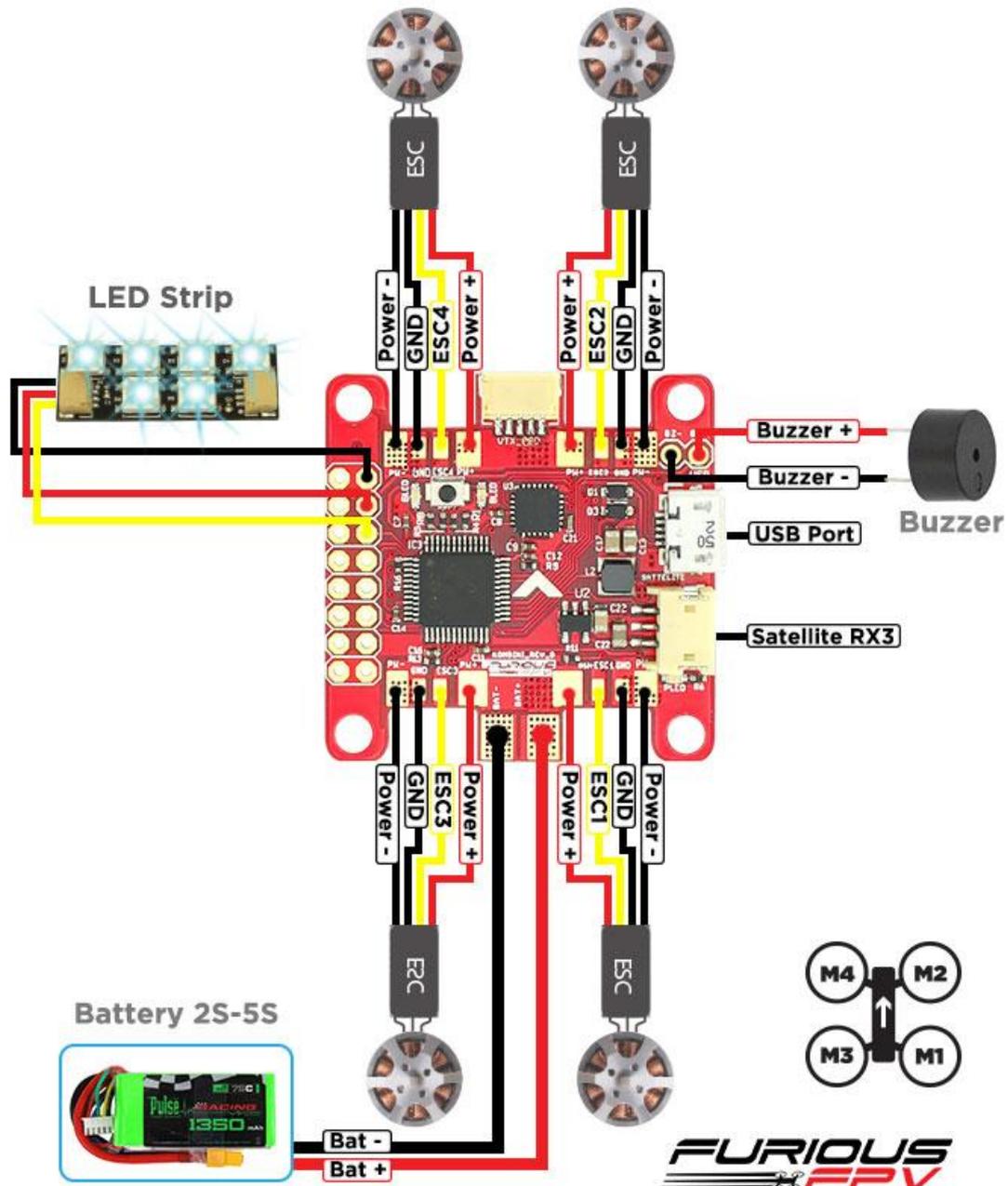
Ports

Note: not all combinations are valid. When the flight controller firmware detects this the serial port configuration will be reset.
 Note: Do NOT disable MSP on the first serial port unless you know what you are doing. You may have to reflash and erase your configuration if you do.

Port Identifier	Configuration	Serial Rx	Telemetry Output	Sensor Input	Peripherals
USB VCP	<input checked="" type="checkbox"/> MSP 115200 ▾	<input type="checkbox"/> Serial Rx	Disabled ▾ AUTO ▾	Disabled ▾ AUTO ▾	Disabled ▾ AUTO ▾
UART1	<input type="checkbox"/> MSP 115200 ▾	<input type="checkbox"/> Serial Rx	Disabled ▾ AUTO ▾	Disabled ▾ AUTO ▾	Disabled ▾ AUTO ▾
UART2	<input type="checkbox"/> MSP 115200 ▾	<input type="checkbox"/> Serial Rx	Disabled ▾ AUTO ▾	Disabled ▾ AUTO ▾	Disabled ▾ AUTO ▾
UART3	<input type="checkbox"/> MSP 115200 ▾	<input type="checkbox"/> Serial Rx	Disabled ▾ AUTO ▾	Disabled ▾ AUTO ▾	Disabled ▾ AUTO ▾

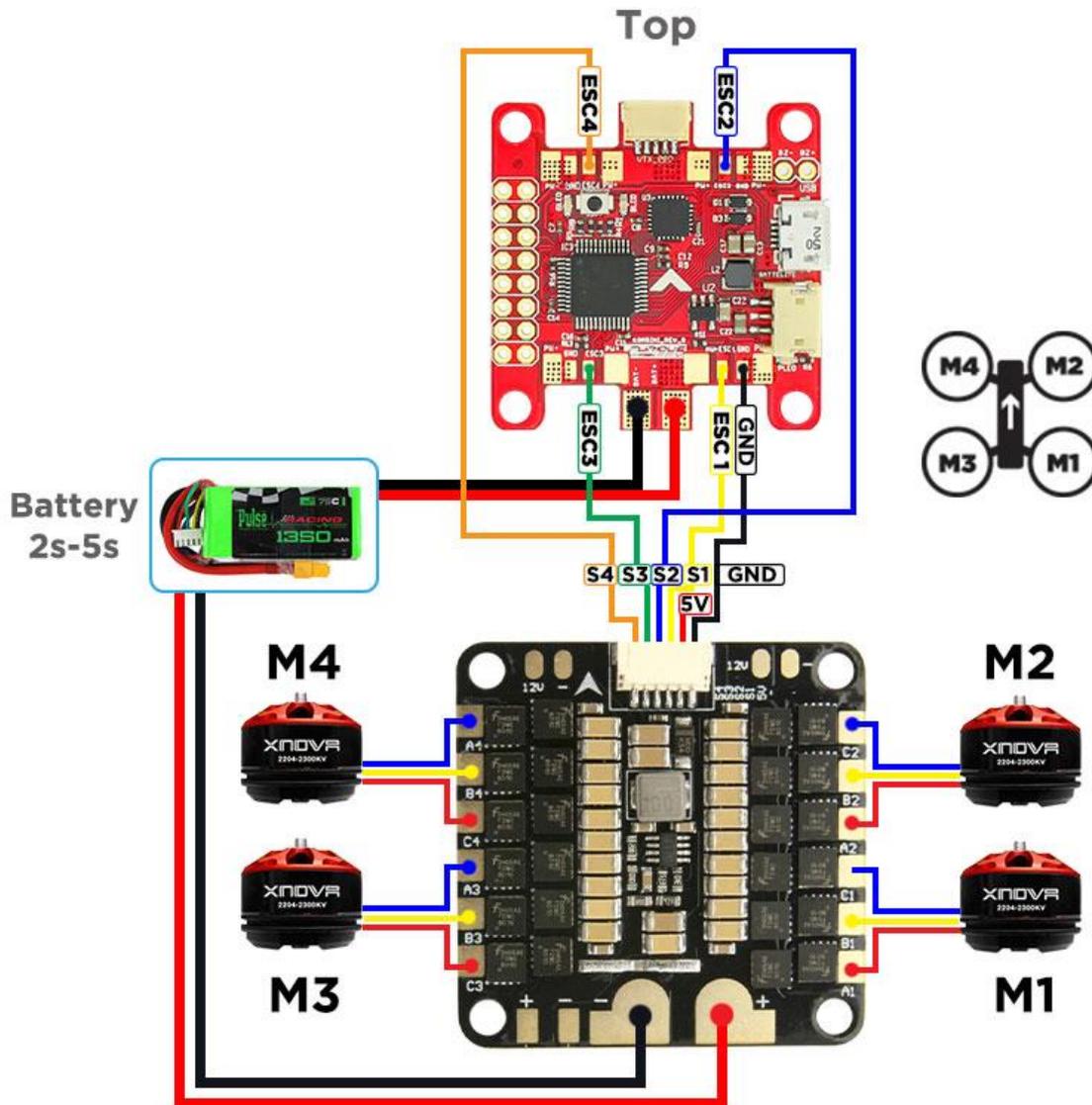


Connect with other devices:



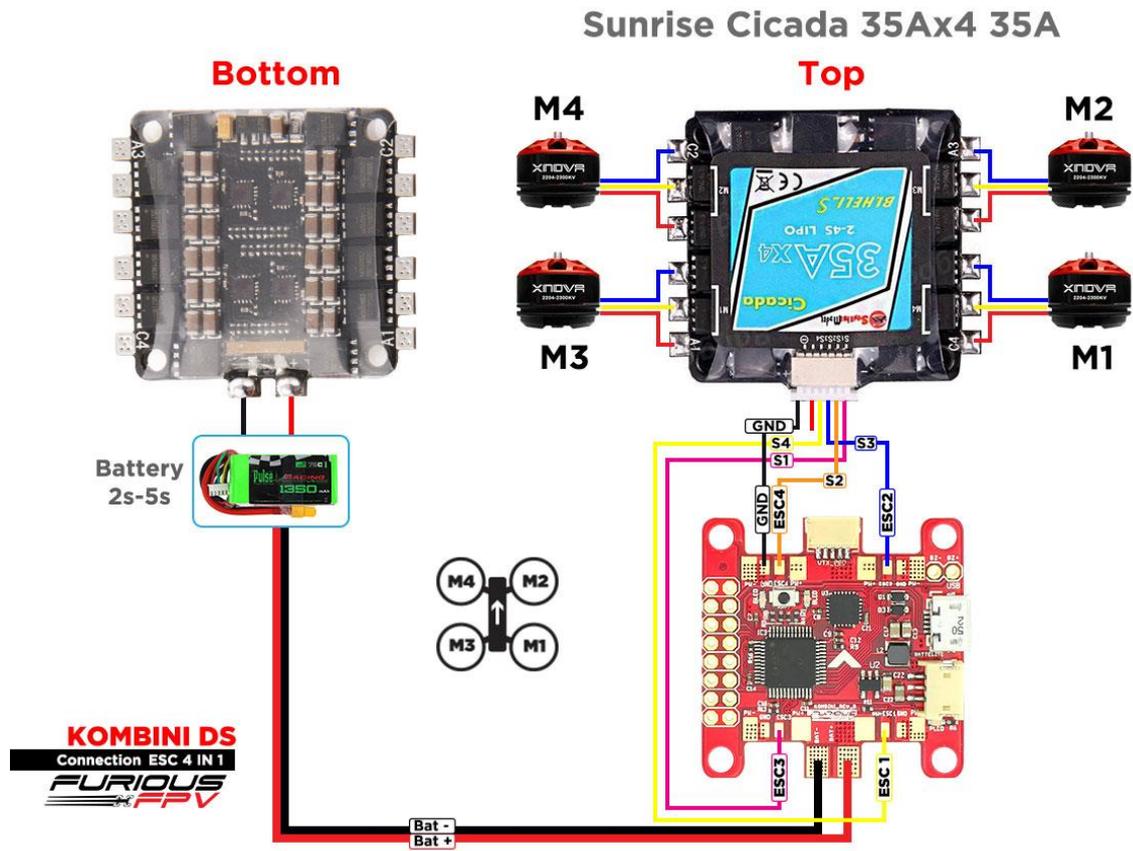
Connect with ESC 4 in 1 Aikon SEFM 30A:

You can buy ESC Aikon SEFM 30 4 in 1 right here: <https://goo.gl/IOYBEr>



Connect with ESC 4 in 1 Cicada 35x4 35A:

You can buy ESC Sunrise Cicada 35x4 35A right here: <https://goo.gl/s080a1>



Basic setup

Please, follow carefully these next steps, and always **remove** your propellers when you're configuring your quad

Step 1: Plug USB cable and **connect** Kombini with the computer then **open** BetaFlight

Step 2: Configure Ports.

- (1) Turn on **MSP** of **UART 1** to use OSD.
- (2) Turn on **Serial Rx** of **UART 3** to use **Receiver Mode**
- (3) Select **SmartPort** of **UART 2** to use **S.Port** of Receiver.

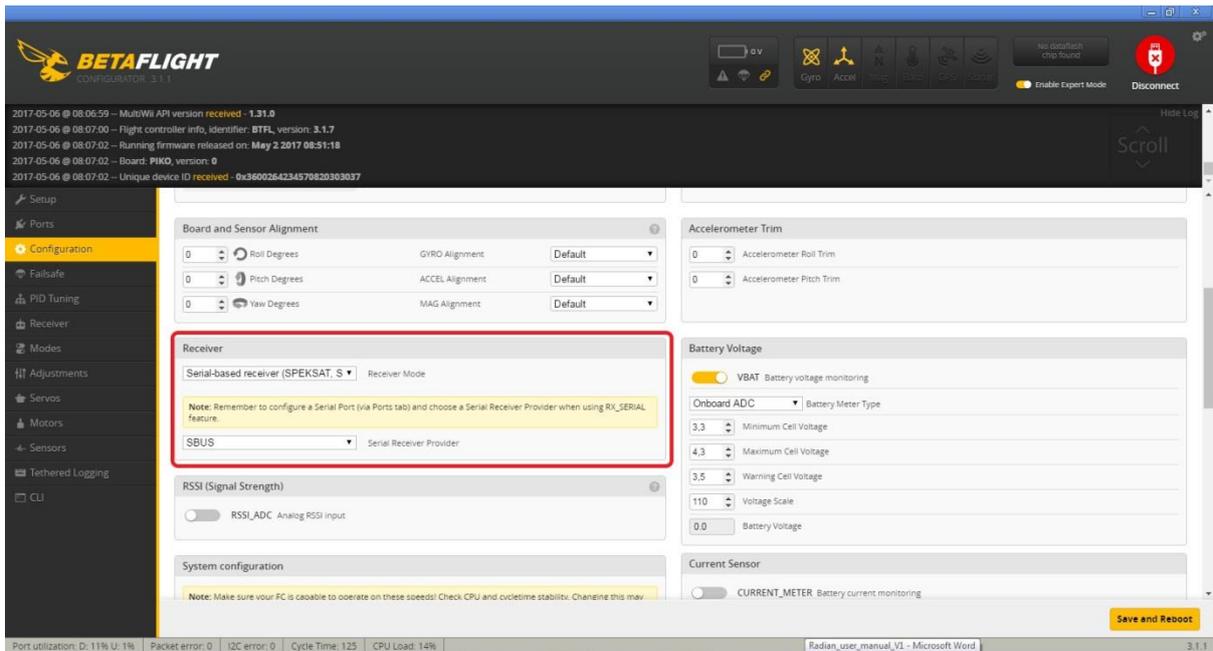
Port Identifier	Configuration	Serial Rx	Telemetry Output	Sensor Input	Peripherals
USB VCP	<input type="checkbox"/> MSP 115200	<input type="checkbox"/> Serial RX	Disabled AUTO	Disabled AUTO	Disabled AUTO
UART1	<input checked="" type="checkbox"/> MSP 115200	<input type="checkbox"/> Serial RX	Disabled AUTO	Disabled AUTO	Disabled AUTO
UART2	<input type="checkbox"/> MSP 115200	<input type="checkbox"/> Serial RX	SmartPort AUTO	Disabled AUTO	Disabled AUTO
UART3	<input type="checkbox"/> MSP 115200	<input checked="" type="checkbox"/> Serial RX	Disabled AUTO	Disabled AUTO	Disabled AUTO

*** Note:** Please check in connection to correct select for this function.

Step 3: Go to Configuration and choose **ESC/Motor** protocol in ESC/Motor Features

The screenshot shows the Betaflight Configuration interface. The 'ESC/Motor Features' section is highlighted with a red box, showing a dropdown menu with 'DSHOT600' selected. Other options include PWM, ONESHOT125, ONESHOT42, MULTISHOT, BRUSHED, DSHOT150, and DSHOT300. The interface also shows a mixer diagram, board and sensor alignment settings, and accelerometer trim options.

Step 4: Select Serial- based receiver in Receiver Mode



If you are using SBus, iBus or a Spektrum Satellite, you will need to pick your Serial Receiver Provider. Follow this table:

RX Type	Serial Receiver Provider
DSM2 Satellite	SPEKTRUM1024
DSMX Satellite	SPEKTRUM2048
FrSky RX	SBUS
Futaba RX	SBUS
FlySky RX	IBUS
Turnigy RX	IBUS

Ex: If you use **SPD15** or **XSR Receiver** then you choose **SBUS** in Serial Receiver Provider.

Go to **CLI** and type the following commands:

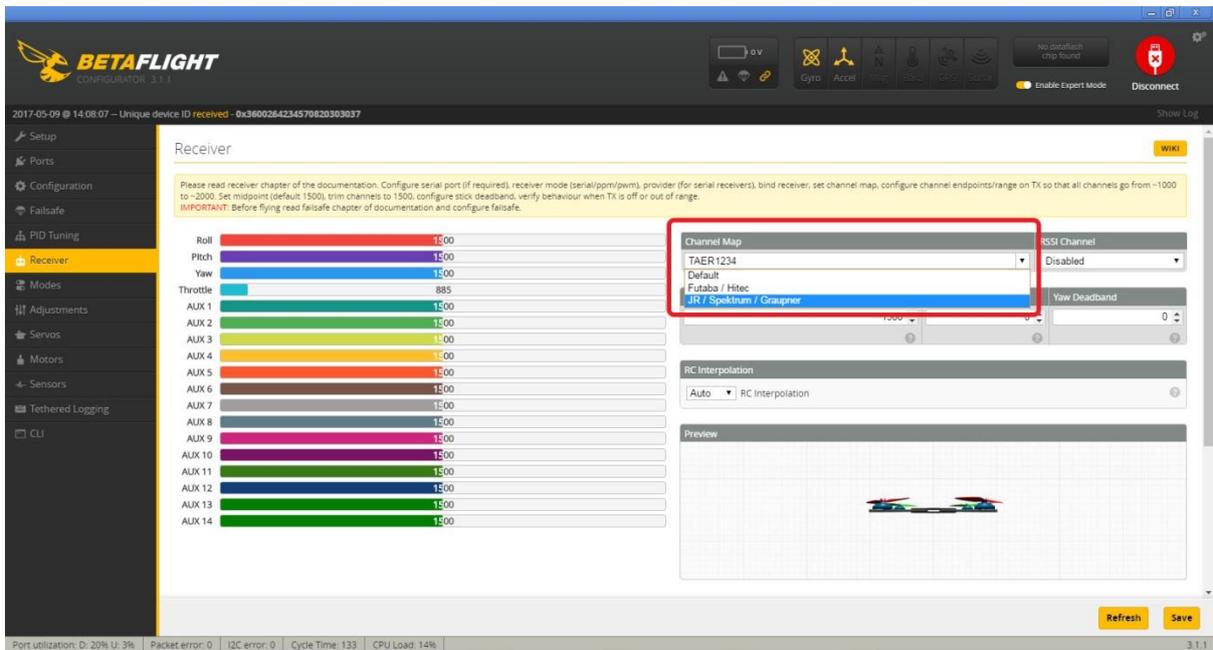
```
set sbus_inversion = ON
save
```

If you use **LR1000D** Receiver please type:

```
set sbus_inversion = ON
save
```

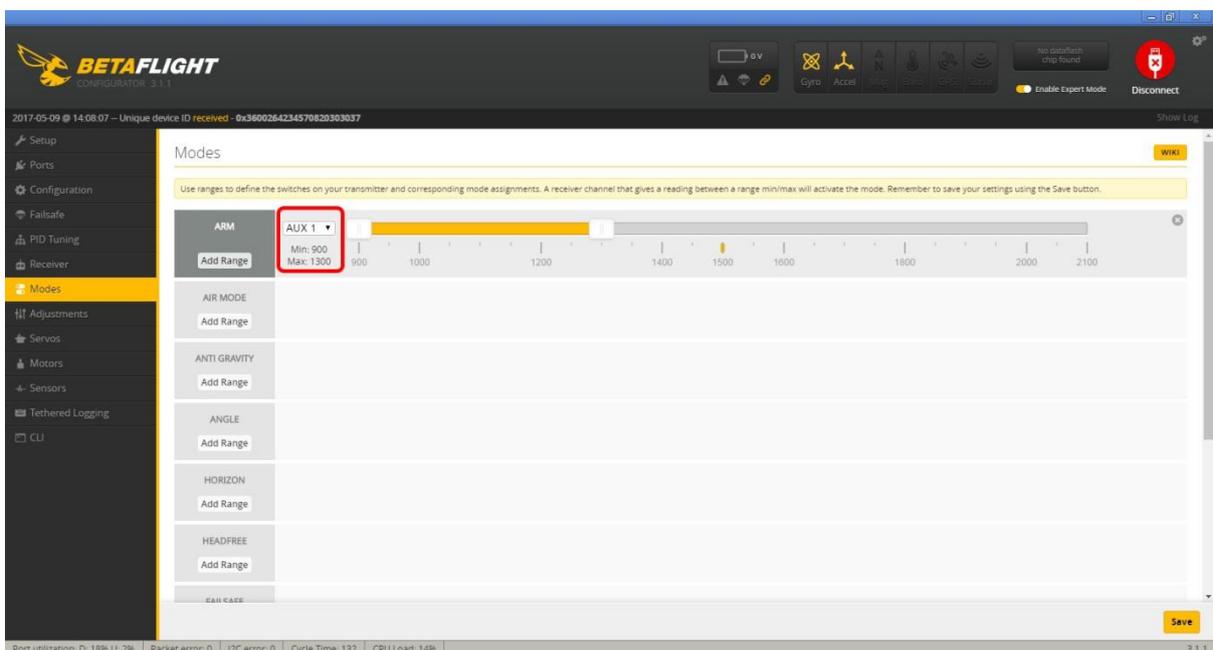
Step 5: Go to **Receiver** tab to configure the receiver and select the **channel mapping** compatible with your transmitter.

Ex: Choose 3rd mapping (JR/ Spektrum/ Graupner) if you use **FrSky** Receiver.



Step 6: Go to **Modes** to set **ARM range** and choose auxiliary functions Aux.

* Note: the Aux number associated with the switch you will use for arming, other modes function

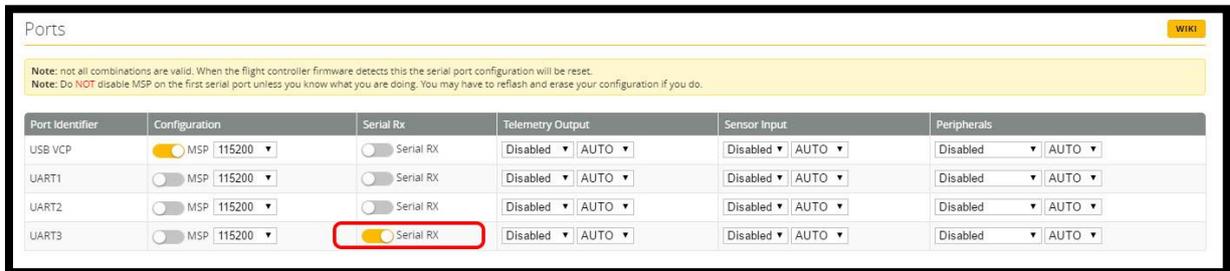


Tips

How to configure your Spektrum RX with your flight controller:

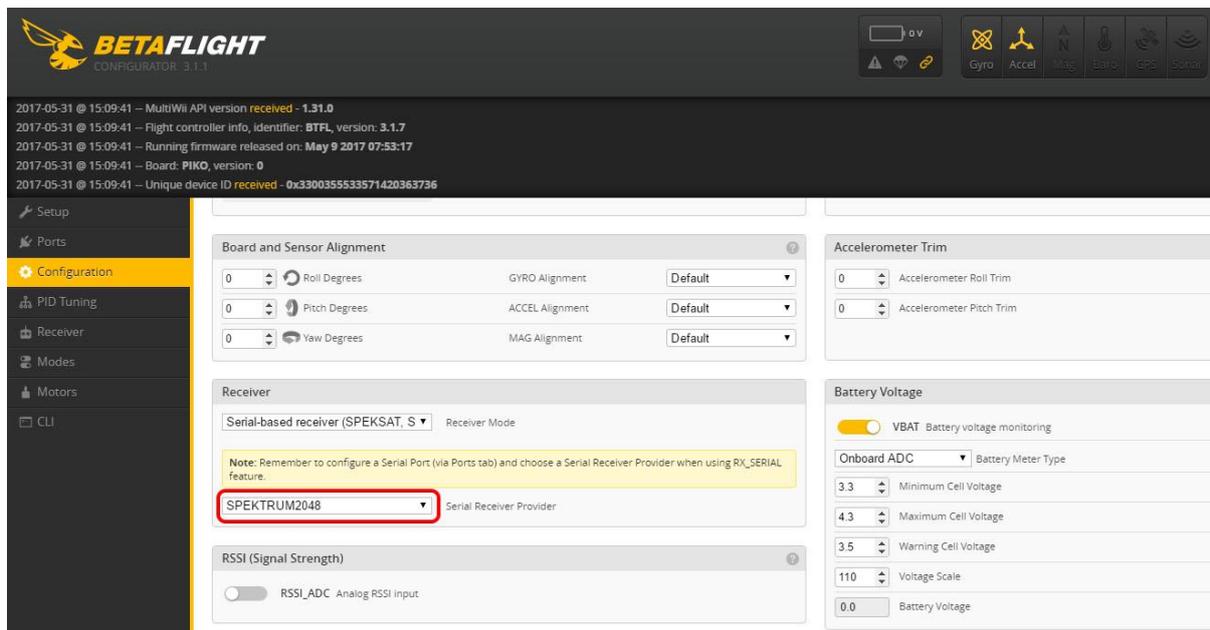
In Betaflight Configurator:

- Go to the **Ports** tab
- Enable **“Serial RX”** on the UART 3



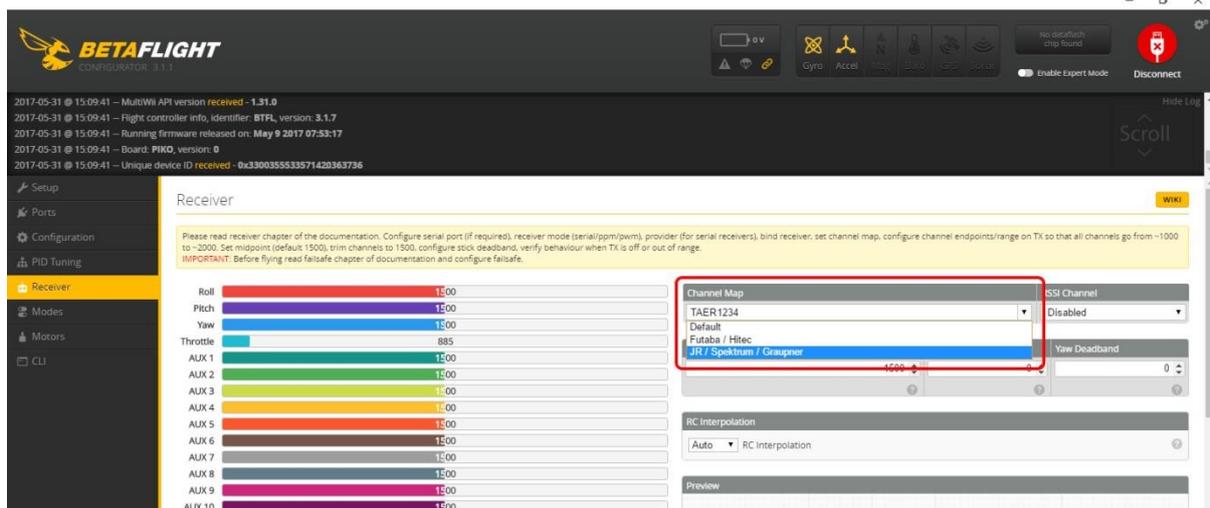
Click **“Save”**.

Then go to the **Configuration** tab. Under the section labeled **“Receiver”**, pick **SPEKTRUM2048**. (Note: If you are using a **DSM2** receiver, pick **SPEKTRUM1024**.)



Click **“Save”**.

Finally, go to the **Receiver** tab. Pull down the drop down that says “Channel Map” and select the “JR / Spektrum / Graupner” option.

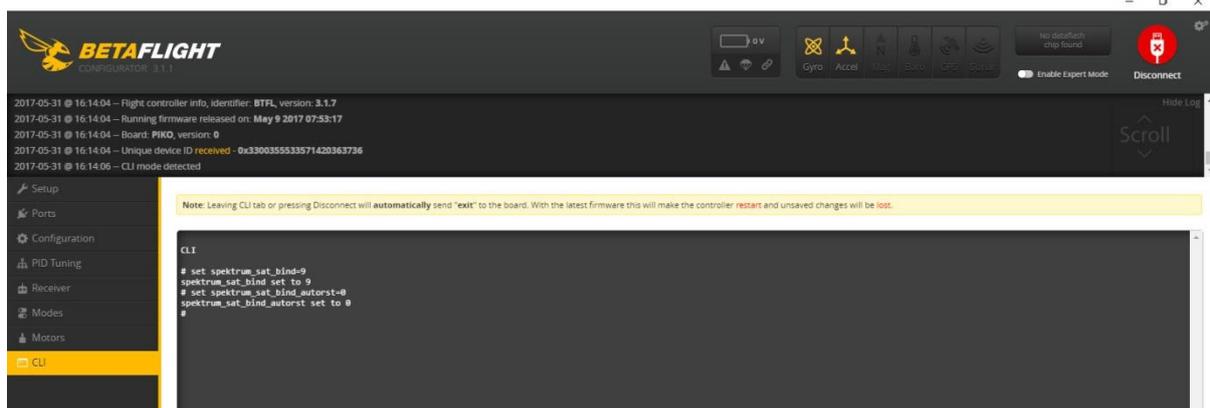


Once again, click “Save”.

How to turn on bind mode

Safety warning: never plug battery to the quad during setup.

Connect quadcopter to the computer and go to Command-line interface (CLI) tab.



Remember to type “save” and hit **enter** after these commands have been executed.

Type in the commands as pictured above, or copy and paste them from below:

set spektrum_sat_bind=9

set spektrum_sat_bind_autorst=0

save

Note – if you are using a **DSM2 receiver**, change “set spektrum_sat_bind=9” to

“set spektrum_sat_bind=5”

Reboot your flight controller by unplugging the flight controller from your PC then plugging it back in.

Your RX should go into bind mode by now as the LED on the RX will be blinking rapidly.

How to set up OSD via BetaFlight Serialpassthrough:

Note:

- UART 1 is typically reserved for the USB so if you have connected anything you want to access on that UART, this will not work
- Depending on your setup you may need to power the device you are trying to connect to access it.

How to set up OSD with BetaFlight via Serialpassthrough:

Step 1: Connect your flight controller to the USB on your computer.

Step 2: Open **Betaflight** and connect to the flight controller while noting the com port it's using.

Step 3: Go to the **Ports** tab and verify what UART you've connected to your device.

The screenshot shows the BetaFlight software interface with the 'Ports' tab selected. The interface displays a table of port configurations. The UART1 row is highlighted with a red box, indicating it is the selected port. The table shows the following configurations:

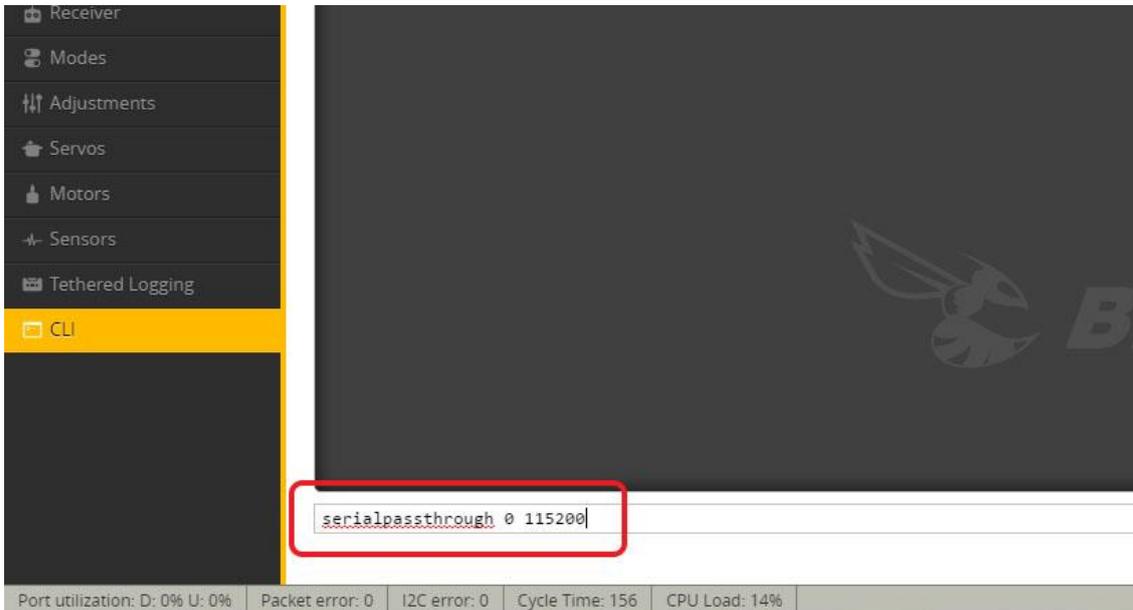
Port Identifier	Configuration	Serial Rx	Telemetry Output	Sensor Input	Peripherals
USB VCP	<input checked="" type="checkbox"/> MSP 115200	<input type="checkbox"/> Serial RX	Disabled AUTO	Disabled AUTO	Disabled AUTO
UART1	<input checked="" type="checkbox"/> MSP 115200	<input type="checkbox"/> Serial RX	Disabled AUTO	Disabled AUTO	Disabled AUTO
UART2	<input type="checkbox"/> MSP 115200	<input type="checkbox"/> Serial RX	Disabled AUTO	Disabled AUTO	Disabled AUTO
UART3	<input type="checkbox"/> MSP 115200	<input type="checkbox"/> Serial RX	Disabled AUTO	Disabled AUTO	Disabled AUTO

At the bottom of the interface, there is a status bar showing various system metrics: Port unstream: 0, 10% u: 1% | Packet error: 0 | IQC error: 0 | Cycle Time: 131 | GPU Load: 14% | 3.1.1

Step 4: Go to the CLI tab and type the following: `serialpassthrough (port) (baud)`

At here, my OSD connected to UART1 so you need to type:

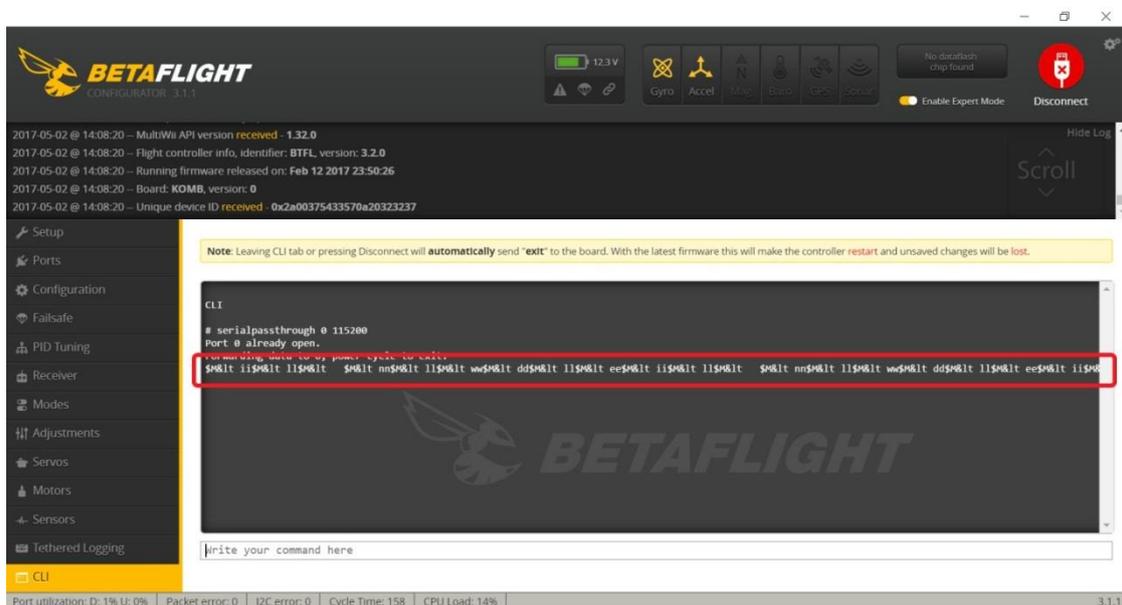
`serialpassthrough 0 115200`



NOTE: Betaflight labels serial ports starting from 0 not 1 yet most flight controllers label UART's starting with 1. So when selecting your serial port you will typically take whatever the UART number is and subtract 1 to get the serial port it's asking for.

Step 4: Power up the device you are trying to connect to if it's not already

You will see what looks like random characters, start scrolling under the command you ran if it's working properly.



Step 5: Disconnect and close Betaflight but leave all the connections as they are.

Step 6: Open up your software you use to configure it. In my case it was MW OSD GUI.

Step 7: Select the **port** you noted in Betaflight being used to **connect** to your flight controller and connect.



Step 8: You should have read/write access now to the device.

When you're done all you need to do is reset the flight controller via reset button or unplugging USB and battery. This will remove the serialpassthrough so you can once again access it via Betaflight.